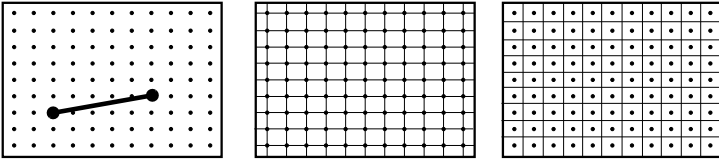


Drawing Lines

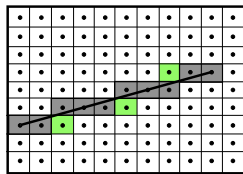
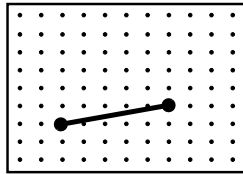
- frame buffer coordinates



Drawing Lines

(scan conversion/rasterization)

- Given: (x_1, y_1) , (x_2, y_2)
- want:
 - straight
 - consistent density
 - speed
 - integer
 - incremental



Drawing Lines

- incremental methods

$$y = mx + b$$

$$m = \frac{\Delta y}{\Delta x}$$

$$y_{i+1} = m(x_{i+1}) + b = m(x_i + \Delta x) + b$$

$$y_{i+1} = y_i + m\Delta x$$

if $\Delta x = 1$

$$y_{i+1} = y_i + m$$

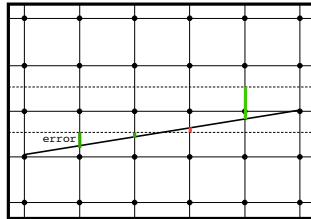
Simple DDA

```
DrawLine(int x1, int y1, int x2, int y2) {
    int x
    double dx, dy, y, m
    dx = x2-x1
    dy = y2-y1
    m = dy/dx
    y = y1;
    for (x = x1; x <= x2; x++) {
        SetPixel(x, round(y))
        y += m
    }
}
```

- assumes $-1 < m < 1$
- problems:
 - floating pt
 - round()
- workaround:
 - add 0.5 to y and truncate

Bresenham's Alg 1962

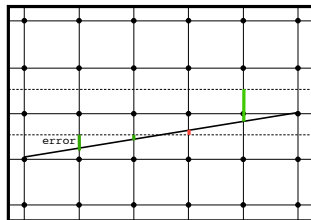
```
DrawLine(int x1,int y1,int x2,int y2){
    int x, y
    double dx, dy, error
    dx = x2-x1
    dy = y2-y1
    error = dy/dx - 0.5
    y = y1;
    for (x = x1; x <= x2; x++) {
        SetPixel(x, y)
        if (error > 0.0) {
            y++
            error = error - 1.0
        }
        error = error + dy/dx
    }
}
```



- error = distance between half-way point and true line at next step
- problems:
 - division
 - floating point

Bresenham's Alg

```
DrawLine(int x1,int y1,int x2,int y2){
    int x, y, dx, dy, error
    dx = x2-x1
    dy = y2-y1
    error = 2*dy-dx
    y = y1;
    for (x = x1; x <= x2; x++) {
        SetPixel(x, y)
        if (error > 0) {
            y++
            error = error - 2*dx
        }
        error = error + 2*dy
    }
}
```

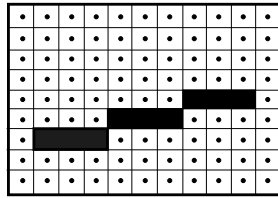


- multiply error by $2*dx$ (only care about sign)
- developed in 1960s
- pen plotters

Smoothing Lines

Anti-Aliasing

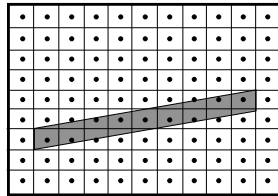
- jagged lines
- staircasing
- also known as aliasing
(need to perform anti-aliasing)
- static bad, motion worse



Area Averaging

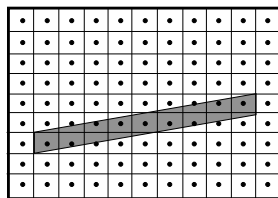
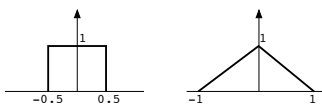
- contribution proportional to area within pixel square

$$I'(x_0, y_0) = \int_{x_0-0.5}^{x_0+0.5} \int_{y_0-0.5}^{y_0+0.5} I(x, y) dx dy$$



Weighed Area Averaging

- filtering theory encourages use of weighed area averaging
- filter has higher value closer to centre

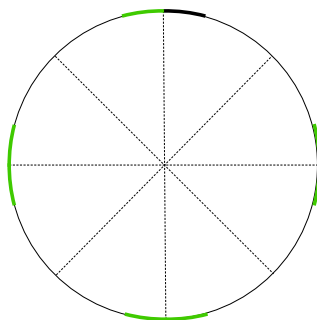


$$I'(x_0, y_0) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} I(x, y) F(x_0 - x, y_0 - y) dx dy$$

- overlap across pixel squares
- weighed filter normalized

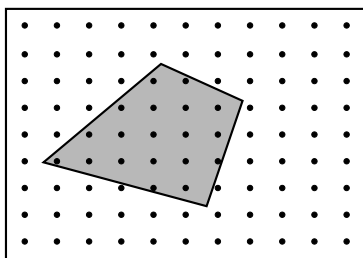
Drawing Circles

- 8-fold symmetry
- do just 1 octant and mirror the rest
- modified Bresenham



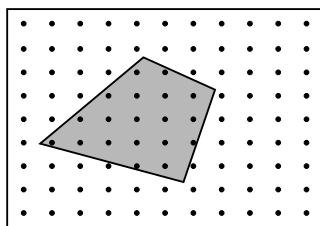
Polygon Rasterization

- given: list of vertices
generate: interior pixels



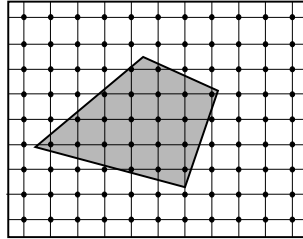
Polygon Rasterization

- given: list of vertices
generate: interior pixels
- types of polygons:
 - rectangular, axis-aligned
 - convex
 - concave
 - concave, with holes, self-intersecting



Convex Polygons

- find top vertex
- go down left and right sides
- compute intersections with scanline
- draw horizontal runs on each scan line

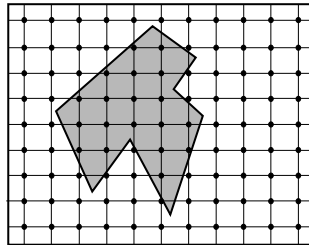


- *incremental*
- *amortize edge computations*

Concave

For each scanline:

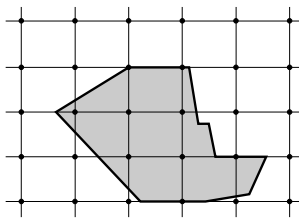
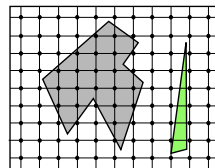
- find intersection of scanline and edges of polygon
- sort intersections by increasing x value
- fill in pixels between pairs of intersection points



can also handle holes

Issues

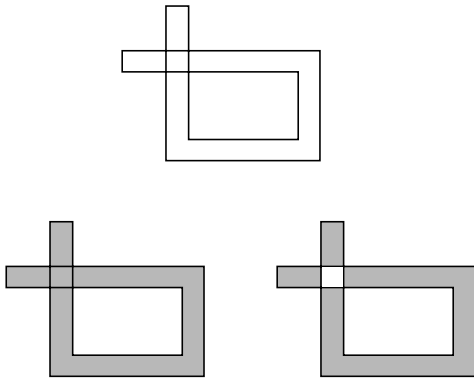
- slivers
 - horizontal edges
 - vertices with integer y coords
- [...)



Speeding Up Concave

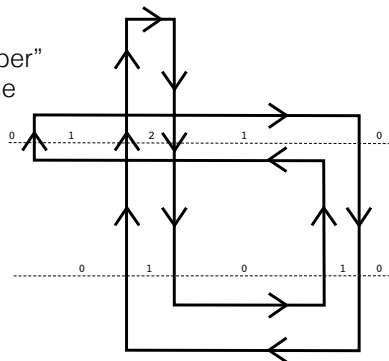
- rely on edge and scanline **coherence** (the extent to which image is locally the same)
- sort edges w.r.t. max y
- compute active edges (edges that intersect current scanline) by going down sorted edge list and adding new edges
- intersect scanline with active edges to get intersection points
- draw visible spans
- go to next scanline (throw out old edges, get new active edges)

Self-Intersecting?



Newell & Sequin

- VLSI
- compute “winding number” as you go along scanline
- edge going up: +1
- edge going down: -1
- draw non-zero spans



Newell & Sequin

- can also do holes
- hole edges labeled in opposite direction

